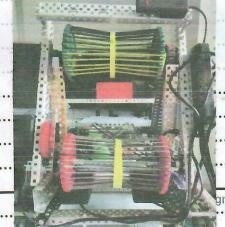


difficult to see that the biggest advantages of the device is the fast speed and continuous. However, after a lot of time of training, we found following disadvantages:

- 1. The stability is not high enough, and it can not accurately control the point of the Triball falling down.
- 2. The launch trajectory is single. When the oppnent Robot come to block, it can not launch the Iriball to the design position.





project

gned by: <evin

witnessed by: TZY

date: 627