

☒ Disadvantages

1. The trajectory is unstable. Sometimes the Triball will even fall into our defensive zone.
2. The Triball is separate from our Robot. So it is hard to handle them after launching and the opponent can push Triball back easily.
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☒ PLAN B Through Channel

☒ Advantages

1. After pushing Triballs to the opponent's defensive zone, we can also push them into the Goal.
2. In the first 1'15", the opponent's Robot can defence, but they have to stay at the corner and pay attention to the time limit of "holding" status. It can be a really good way to interfere the opponent by reduce their efficiency.
3. In the last 30' sec. Elevation is protected. The opponent's Robot cannot contact our Robot <SGII>. So we can easily score and push Triballs into the Goal.

☒ Disadvantages

1. If the opponent's Robot stay in the Load position, it can