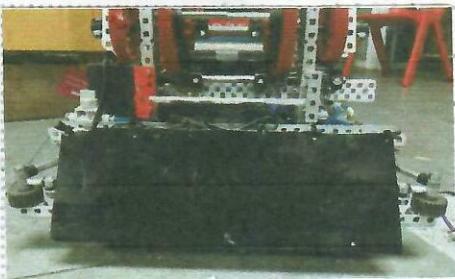


4/11

**Kevin** Considering the antagonistic intensity, we add an idler pulley at the empennage of the Robot.

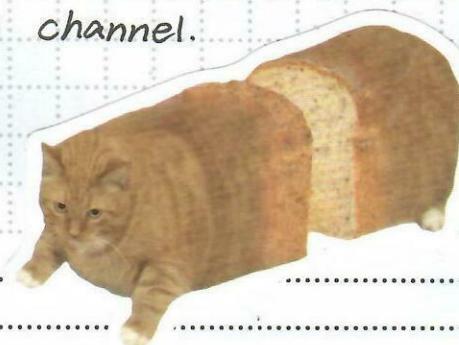
**Martin** Sometimes we use the empennage to push Triballs into the Goal. Compared to using the headstock, using the empennage to strick Triballs can get more into the Goal and its efficient is higher. And if we add a PVC board, the impact surface will be flatter.

**Kevin** It needs to be an active board. or it may get stuck when the Robot driven over the long barrier pole. So we use a rubber band to immobilise the PVC board



And we found that there is another use of idler pulley. It can broaden the width of the empennage, so pushing the Triball into the Goal idler pulley Can be much more easily.

**Martin** We change the plastic gear to the metal idler pulley. It can be much more smooth when the Robot entering the channel.



project

V4

designed by: Kevin

witnessed by: Jeker

date: 11.4