

a certain impact on the overall handling performance. During turns, the chassis speed has noticeably increased, leading to tire slippage. This has presented some challenges, especially in accurately aligning the suction of individual Triballs.

- ① To address the issue of drifting during turns, I believe that adjustments can be made to the program.

It may be necessary to reassess the response speed and intensity of the steering system to ensure better control of chassis stability and reduce tire slippage during turns.

- ② For the problem of pushing Triballs through the channel, I realize that more practice and training are needed.

When exiting the channel, I realize that control the speed to minimize excessive Triball pushing is significant. Additionally, I plan to improve my proficiency and adaptability in operating through repeated practice and exploration of different techniques.

In conclusion, for this Robot that has undergone chassis acceleration and weight reduction modifications, I'll focus on the issue of drifting.

project

U5

designed by: Steven

witnessed by: Kevin

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