VEX "Never doubt that a small group of thoughtful, committed citizens can change the world. Indeed, it is the only thing that ever has." - Margaret Mead.

97

ward function and turning function, which can jump out of this command and execute the next command. It can prevent Robot from iterrupting the whole program when it cannot reach the predetermined value.

⊗ vl & vr (control the chassis motors)

vl: the power of the left motor
vr: the power of the right motor

In this way, the Robot can move in an arc.

⊗ spin

Due to the change in the way ₮ of taking out the Triball in the corner, we add the function "spin" to control the cylinder. But it cannot being used in the driver control period.

✕ In addition, Before the driver control period, I add a function to detect the satus of the catapult. It can change it to the lowered state to ensure the Robot can smoothly pass the pole.

project Vs - Program   designed by: Joker   witnessed by: Steven
                                                                    date: 12.3

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